

Four Output Differential Buffer for PCle Gen 1 and Gen 2

ICS9DB403D

Description

The ICS9DB403 is compatible with the Intel DB400v2 Differential Buffer Specification. This buffer provides 4 PCI-Express Gen2 clocks. The ICS9DB403 is driven by a differential output pair from a CK410B+, CK505 or CK509B main clock generator.

Output Features

- 4 0.7V current-mode differential output pairs
- Supports zero delay buffer mode and fanout mode
- · Bandwidth programming available
- 50-100 MHz operation in PLL mode
- 50-400 MHz operation in Bypass mode

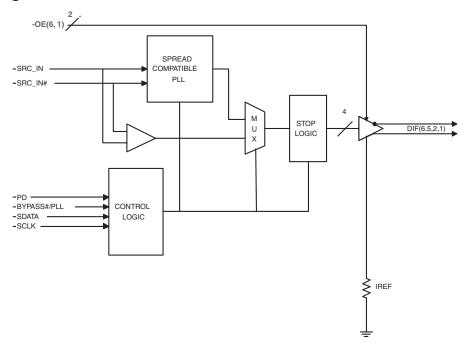
Features/Benefits

- Spread spectrum modulation tolerant, 0 to -0.5% down spread and +/- 0.25% center spread.
- Supports undriven differential outputs in PD# and SRC_STOP# modes for power management.

Key Specifications

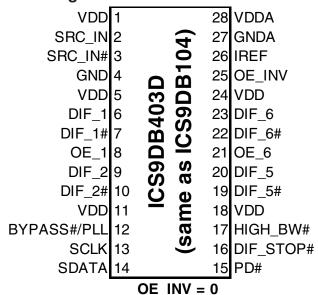
- Outputs cycle-cycle jitter < 50ps
- Outputs skew: 50ps
- Phase jitter: PCle Gen1 < 86ps peak to peak
- Phase jitter: PCle Gen2 < 3.0/3.1ps rms
- 28-pin SSOP/TSSOP pacakge
- · Available in RoHS compliant packaging
- Supports Commercial (0 to +70°C) and Industrial (-40 to +85°C) temperature ranges

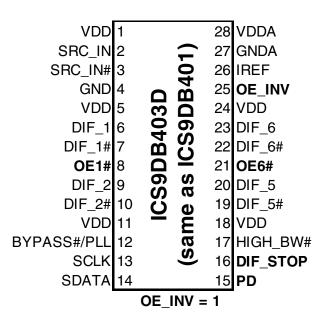
Functional Block Diagram



Note: Polarities shown for $OE_INV = 0$.

Pin Configuration





28-pin SSOP & TSSOP

Polarity Inversion Pin List Table

	OE_INV				
Pins	0	1			
8	OE_1	OE1#			
15	PD#	PD			
16	DIF_STOP#	DIF_STOP			
21	OE_6	OE6#			

Power Groups

Pin N	lumber	Description			
VDD	GND	Description			
1	4	SRC_IN/SRC_IN#			
5,11,18, 24	4	DIF(1,2,5,6)			
N/A	27	IREF			
28	27	Analog VDD & GND for PLL core			

Pin Decription When OE_INV = 0

PIN#	PIN NAME	PIN TYPE	DESCRIPTION
1	VDD	PWR	Power supply, nominal 3.3V
2	SRC_IN	IN	0.7 V Differential SRC TRUE input
3	SRC_IN#	IN	0.7 V Differential SRC COMPLEMENTARY input
4	GND	PWR	Ground pin.
5	VDD	PWR	Power supply, nominal 3.3V
6	DIF_1	OUT	0.7V differential true clock output
7	DIF_1#	OUT	0.7V differential Complementary clock output
	05.4		Active high input for enabling output 1.
8	OE_1	IN	0 = tri-state outputs, 1= enable outputs
9	DIF_2	OUT	0.7V differential true clock output
10	DIF_2#	OUT	0.7V differential Complementary clock output
11	VDD	PWR	Power supply, nominal 3.3V
10	DVDACC#/DLL	INI	Input to select Bypass(fan-out) or PLL (ZDB) mode
12	BYPASS#/PLL	IN	0 = Bypass mode, 1= PLL mode
13	SCLK	IN	Clock pin of SMBus circuitry, 5V tolerant.
14	SDATA	I/O	Data pin for SMBus circuitry, 3.3V tolerant.
			Asynchronous active low input pin used to power down the device. The
15	PD#	IN	internal clocks are disabled and the VCO and the crystal osc. (if any) are
			stopped.
16	DIF_STOP#	IN	Active low input to stop differential output clocks.
17	HIGH_BW#	IN	3.3V input for selecting PLL Band Width
17		IIN	0 = High, 1= Low
18	VDD	PWR	Power supply, nominal 3.3V
19	DIF_5#	OUT	0.7V differential Complementary clock output
20	DIF_5	OUT	0.7V differential true clock output
21	OE_6	IN	Active high input for enabling output 6.
			0 = tri-state outputs, 1= enable outputs
22	DIF_6#	OUT	0.7V differential Complementary clock output
23	DIF_6	OUT	0.7V differential true clock output
24	VDD	PWR	Power supply, nominal 3.3V
25	OE_INV	IN	This latched input selects the polarity of the OE pins.
2.5	OL_IIIV	11 V	0 = OE pins active high, 1 = OE pins active low (OE#)
			This pin establishes the reference current for the differential current-mode
26	IREF	OUT	output pairs. This pin requires a fixed precision resistor tied to ground in order
			to establish the appropriate current. 475 ohms is the standard value.
27	GNDA	PWR	Ground pin for the PLL core.
28	VDDA	PWR	3.3V power for the PLL core.

Pin Decription When OE_INV = 1

PIN#	PIN NAME	PIN TYPE	DESCRIPTION		
1	VDD	PWR	Power supply, nominal 3.3V		
2	SRC_IN	IN	0.7 V Differential SRC TRUE input		
3	SRC_IN#	IN	0.7 V Differential SRC COMPLEMENTARY input		
4	GND	PWR	Ground pin.		
5	VDD	PWR	Power supply, nominal 3.3V		
6	DIF_1	OUT	0.7V differential true clock output		
7	DIF_1#	OUT	0.7V differential Complementary clock output		
8	OE1#	IN	Active low input for enabling DIF pair 1. 1 = tri-state outputs, 0 = enable outputs		
9	DIF_2	OUT	0.7V differential true clock output		
10	DIF_2#	OUT	0.7V differential Complementary clock output		
11	VDD	PWR	Power supply, nominal 3.3V		
10	DVD400#/DL1	INI	Input to select Bypass(fan-out) or PLL (ZDB) mode		
12	BYPASS#/PLL	IN	0 = Bypass mode, 1= PLL mode		
13	SCLK	IN	Clock pin of SMBus circuitry, 5V tolerant.		
14	SDATA	I/O	Data pin for SMBus circuitry, 3.3V tolerant.		
15	PD	IN	Asynchronous active high input pin used to power down the device. The internal clocks are disabled and the VCO is stopped.		
16	DIF_STOP	IN	Active High input to stop differential output clocks.		
47		18.1	3.3V input for selecting PLL Band Width		
17	HIGH_BW#	IN	0 = High, 1= Low		
18	VDD	PWR	Power supply, nominal 3.3V		
19	DIF_5#	OUT	0.7V differential Complementary clock output		
20	DIF_5	OUT	0.7V differential true clock output		
21	OE6#	IN	Active low input for enabling DIF pair 6. 1 = tri-state outputs, 0 = enable outputs		
22	DIF_6#	OUT	0.7V differential Complementary clock output		
23	 DIF_6	OUT	0.7V differential true clock output		
24	VDD	PWR	Power supply, nominal 3.3V		
25	OE_INV	IN	This latched input selects the polarity of the OE pins. 0 = OE pins active high, 1 = OE pins active low (OE#)		
26	IREF	OUT	This pin establishes the reference current for the differential current-mode output pairs. This pin requires a fixed precision resistor tied to ground in order to establish the appropriate current. 475 ohms is the standard value.		
27	GNDA	PWR	Ground pin for the PLL core.		
28	VDDA	PWR	3.3V power for the PLL core.		

Absolute Max

Symbol	Parameter	Min	Max	Units
VDD_A	3.3V Core Supply Voltage		4.6	V
VDD_In	3.3V Logic Supply Voltage		4.6	V
V_{IL}	Input Low Voltage	GND-0.5		V
V_{IH}	Input High Voltage		V _{DD} +0.5V	V
Ts	Storage Temperature	-65	150	°C
Tambient	Commerical Operating Range	0	70	°C
Tamblem	Industrial Operating Range	-40	85	°C
Tcase	Case Temperature		115	°C
	Input ESD protection			
ESD prot	human body model	2000		V

Electrical Characteristics - Clock Input Parameters

 T_A = Tambient for the desired operating range, Supply Voltage V_{DD} = 3.3 V +/-5%

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Input High Voltage - DIF_IN	V _{IHDIF}	Differential inputs (single-ended measurement)	600	800	1150	mV	1
Input Low Voltage - DIF_IN	V _{ILDIF}	Differential inputs (single-ended measurement)	V _{SS} - 300	0	300	mV	1
Input Common Mode Voltage - DIF_IN	V_{COM}	Common Mode Input Voltage	300		1000	mV	1
Input Amplitude - DIF_IN	V_{SWING}	Peak to Peak value	300		1450	mV	1
Input Slew Rate - DIF_IN	dv/dt	Measured differentially	0.4		8	V/ns	1,2
Input Leakage Current	I _{IN}	$V_{IN} = V_{DD}, V_{IN} = GND$	-5		5	uA	1
Input Duty Cycle	d_{tin}	Measurement from differential wavefrom	45		55	%	1
Input Jitter - Cycle to Cycle	J_{DIFIn}	Differential Measurement	0		125	ps	1

¹ Guaranteed by design and characterization, not 100% tested in production.

²Slew rate measured through Vswing min centered around differential zero

Electrical Characteristics - Input/Supply/Common Output Parameters

 T_A = Tambient for the desired operating range, Supply Voltage V_{DD} = 3.3 V +/-5%

TA - Tambient for the desir	ca operating	range, Supply Voltage V _{DD} = 3.3 V +/-3/8					
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Input High Voltage	V _{IHSE}	a =	2		$V_{DD} + 0.3$	V	1
Input Low Voltage	V _{ILSE}	Single Ended Inputs, 3.3 V +/-5%	GND - 0.3		0.8	V	1
Input High Current	I _{IHSE}	$V_{IN} = V_{DD}$	-5		5	uA	1
	I _{IL1}	$V_{IN} = 0 \text{ V}$; Inputs with no pull-up resistors	-5			uA	1
Input Low Current	I	V. = 0 V: Inpute with pull up registers	200				-
	I _{IL2}	$V_{IN} = 0$ V; Inputs with pull-up resistors Full Active, $C_L = Full$ load; Commerical	-200			uA	1
ODBOOG Curanity Comment	I _{DD3.3OPC}	Temp Range		175	200	mA	1
9DB803 Supply Current	I _{DD3.3OPI}	Full Active, C _L = Full load; Industrial Temp Range		190	225	mA	1
	long c	all diff pairs driven, C-Temp		50	60	mA	1
9DB803 Powerdown	I _{DD3.3PDC}	all differential pairs tri-stated, C-Temp		4	6	mA	1
Current	I _{DD3.3PDI}	all diff pairs driven, I-temp		55	65	mA	1
	-000.0001	all differential pairs tri-stated, I-temp		6	8	mA	1
0DB400 0	I _{DD3.3OPC}	Full Active, C_L = Full load; Commerical Temp Range		105	125	mA	1
9DB403 Supply Current	I _{DD3.3OPI}	Full Active, C _L = Full load; Industrial Temp Range		115	150	mA	1
		All diff pairs driven, C-Temp		25	30	mA	1
9DB403 Powerdown	I _{DD3.3PDC}	all differential pairs tri-stated, C-Temp		25	30	mA	1
Current	1	all diff pairs driven, I-Temp		30	35	mA	1
	I _{DD3.3PDI}	all differential pairs tri-stated, I-Temp		3	4	mA	1
January Comme	F _{iPLL}	PCIe Mode (Bypass#/PLL= 1)	50	100.00	110	MHz	1
Input Frequency	F _{iBYPASS}	Bypass Mode ((Bypass#/PLL= 0)	33	-	400	MHz	1
Pin Inductance	L _{pin}				7	nH	1
	C _{IN}	Logic Inputs, except SRC_IN	1.5		5	pF	1
Capacitance	C _{INSRC_IN}	SRC_IN differential clock inputs	1.5		2.7	pF	1,4
,	C _{OUT}	Output pin capacitance	5		6	pF	1
DIL D. L. L.		-3dB point in High BW Mode	2	3	4	MHz	1
PLL Bandwidth	BW	-3dB point in Low BW Mode	0.7	1	1.4	MHz	1
PLL Jitter Peaking	t _{JPEAK}	Peak Pass band Gain		1.5	2	dB	1
Clk Stabilization	T _{STAB}	From V _{DD} Power-Up and after input clock stabilization or de-assertion of PD# to 1st		_	1	ms	1,2
		clock					
Input SS Modulation Frequency	f _{MODIN}	Allowable Frequency (Triangular Modulation)	30		33	kHz	1
		(Triangular Modulation) DIF start after OE# assertion					
OE# Latency	t _{LATOE#}	DIF stop after OE# deassertion	1		3	cycles	1,3
Tdrive_SRC_STOP#	t _{DRVSTP}	DIF output enable after SRC_Stop# de-assertion			10	ns	1,3
Tdrive_PD#	t _{DRVPD}	DIF output enable after PD# de-assertion			300	us	1,3
Tfall	t₅	Fall time of PD# and SRC_STOP#			5	ns	1
Trise	t _R	Rise time of PD# and SRC_STOP#			5	ns	2
SMBus Voltage	V _{MAX}	Maximum input voltage			5.5	V	1
Low-level Output Voltage	V _{MAX} V _{OL}	@ I _{PULLUP}			0.4	V	1
Current sinking at V _{OL}	I _{PULLUP}	יצטננטץ	4		στ	mA	1
SCLK/SDATA		(Max VIL - 0.15) to	_				
Clock/Data Rise Time	t _{RSMB}	(Min VIH + 0.15)			1000	ns	1
SCLK/SDATA	1	(Min VIH + 0.15) to					
Clock/Data Fall Time	t _{FSMB}	(Max VIL - 0.15)	<u> </u>		300	ns	1
SMBus Operating	f	Maximum SMBus operating frequency			100	۲⊔¬	1 5
Frequency	† _{MAXSMB}				100	kHz	1,5
10anamata and buy disalama ana		ation, not 100% tosted in production					

¹Guaranteed by design and characterization, not 100% tested in production.

ICS9DB403D REV L 10/07/09

²See timing diagrams for timing requirements.

³Time from deassertion until outputs are >200 mV

⁴SRC_IN input

⁵The differential input clock must be running for the SMBus to be active

Electrical Characteristics - DIF 0.7V Current Mode Differential Pair

 T_A =Tambient; V_{DD} = 3.3 V +/-5%; C_L =2pF, R_S =33 Ω , R_P =49.9 Ω , R_{REF} =475 Ω

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Current Source Output Impedance	Zo ¹		3000			Ω	1
Voltage High	VHigh	Statistical measurement on single	660		850	.,	1,2
Voltage Low	VLow	ended signal using oscilloscope math function.	-150		150	mV	1,2
Max Voltage	Vovs	Measurement on single ended			1150	mV	1
Min Voltage	Vuds	signal using absolute value.	-300				1
Crossing Voltage (abs)	Vcross(abs)		250		550	mV	1
Crossing Voltage (var)	d-Vcross	Variation of crossing over all edges			140	mV	1
Rise Time	t _r	$V_{OL} = 0.175V, V_{OH} = 0.525V$	175		700	ps	1
Fall Time	t _f	$V_{OH} = 0.525V \ V_{OL} = 0.175V$	175		700	ps	1
Rise Time Variation	d-t _r				125	ps	1
Fall Time Variation	d-t _f				125	ps	1
Duty Cycle	d _{t3}	Measurement from differential wavefrom	45		55	%	1
Ckow Input to Output	t _{pdBYP}	Bypass Mode, V _T = 50%	2500		4500	ps	1
Skew, Input to Output	t _{pdPLL}	PLL Mode V _T = 50%	-250		250	ps	1
Skew, Output to Output	t _{sk3}	V _T = 50%			50	ps	1
Jitter, Cycle to cycle	+	PLL mode			50	ps	1,3
Jitter, Cycle to cycle	t _{jcyc-cyc}	Additive Jitter in Bypass Mode			50	ps	1,3
		PCIe Gen1 phase jitter (Additive in Bypass Mode)		7	10	ps (pk2pk)	1,4,5
	t _{jphaseBYP}	PCIe Gen 2 Low Band phase jitter (Additive in Bypass Mode)		0	0.1	ps (rms)	1,4,5
Jitter, Phase		PCIe Gen 2 High Band phase jitter (Additive in Bypass Mode)		0.3	0.5	ps (rms)	1,4,5
		PCIe Gen 1 phase jitter	-	40	86	ps (pk2pk)	1,4,5
	t _{jphasePLL}	PCIe Gen 2 Low Band phase jitter		1.5	3	ps (rms)	1,4,5
		PCIe Gen 2 High Band phase jitter		2.7/ 2.2	3.1	ps (rms)	1,4,5,6

¹Guaranteed by design and characterization, not 100% tested in production.

 $^{^{2}}$ I_{REF} = V_{DD}/(3xR_R). For R_R = 475 Ω (1%), I_{REF} = 2.32mA. I_{OH} = 6 x I_{REF} and V_{OH} = 0.7V @ Z_O=50 Ω .

³ Measured from differential waveform

⁴ See http://www.pcisig.com for complete specs

⁵ Device driven by 932S421C or equivalent.

⁶ First number is High Bandwidth Mode, second number is Low Bandwidth Mode

Clock Periods Differential Outputs with Spread Spectrum Enabled

Measi	urement				-					
Wi	ndow	1 Clock	1us	0.1s	0.1s	0.1s	1us	1 Clock		
Sy	mbol	Lg-	LgSSC -ppm error 0ppm + ppm error +SSC	+SSC	Lg+					
Definition		Absolute Period	Short-term Average	Long-Term Average	Period	Long-Term Average	Short-term Average	Period		
		Minimum Absolute	Minimum Absolute	Minimum Absolute	Nominal	Maximum	Maximum	Maximum		
		Period	Period	Period					Units	Notes
	DIF 100	9.87400	9.99900	9.99900	10.00000	10.00100	10.05130	10.17630	ns	1,2,3
e e	DIF 133	7.41425	7.49925	7.49925	7.50000	7.50075	7.53845	7.62345	ns	1,2,4
Name	DIF 166	5.91440	5.99940	5.99940	6.00000	6.00060	6.03076	6.11576	ns	1,2,4
<u> </u>	DIF 200	4.91450	4.99950	4.99950	5.00000	5.00050	5.02563	5.11063	ns	1,2,4
Signal I	DIF 266	3.66463	3.74963	3.74963	3.75000	3.75038	3.76922	3.85422	ns	1,2,4
S	DIF 333	2.91470	2.99970	2.99970	3.00000	3.00030	3.01538	3.10038	ns	1,2,4
	DIF 400	2.41475	2.49975	2.49975	2.50000	2.50025	2.51282	2.59782	ns	1,2,4

Clock Periods Differential Outputs with Spread Spectrum Disabled

Meas	urement				•					
Wi	ndow	1 Clock	1us	0.1s	0.1s	0.1s	1us	1 Clock		
Sy	mbol	Lg-	-SSC	-ppm error	0ppm	+ ppm error	+SSC	Lg+		
Definition		Absolute Period	Short-term Average	Long-Term Average	Period	Long-Term Average	Short-term Average	Period		
		Minimum Absolute	Minimum Absolute	Minimum Absolute	Nominal	Maximum	Maximum	Maximum	<u> </u>	
		Period	Period	Period					Units	Notes
	DIF 100	9.87400		9.99900	10.00000	10.00100		10.17630	ns	1,2,3
<u>ə</u>	DIF 133	7.41425		7.49925	7.50000	7.50075		7.62345	ns	1,2,4
Name	DIF 166	5.91440		5.99940	6.00000	6.00060		6.11576	ns	1,2,4
al	DIF 200	4.91450		4.99950	5.00000	5.00050		5.11063	ns	1,2,4
Signal	DIF 266	3.66463		3.74963	3.75000	3.75038		3.85422	ns	1,2,4
S	DIF 333	2.91470		2.99970	3.00000	3.00030		3.10038	ns	1,2,4
1	DIF 400	2.41475		2.49975	2.50000	2.50025		2.59782	ns	1,2,4

¹Guaranteed by design and characterization, not 100% tested in production.

² All Long Term Accuracy specifications are guaranteed with the assumption that the input clock complies with CK409/CK410/CK505 accuracy requirements. The 9DB403/803 itself does not contribute to ppm error.

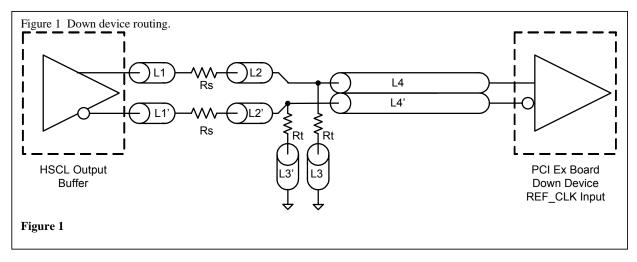
³ Driven by SRC output of main clock, PLL or Bypass mode

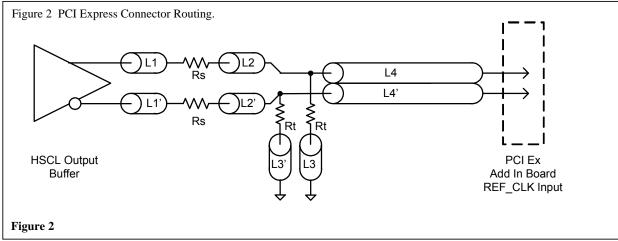
⁴ Driven by CPU output of CK410/CK505 main clock, **Bypass mode only**

SRC Reference Clock								
Common Recommendations for Differential Routing	Dimension or Value	Unit	Figure					
L1 length, Route as non-coupled 50 ohm trace.	0.5 max	inch	1					
L2 length, Route as non-coupled 50 ohm trace.	0.2 max	inch	1					
L3 length, Route as non-coupled 50 ohm trace.	0.2 max	inch	1					
Rs	33	ohm	1					
Rt	49.9	ohm	1					

Down Device Differential Routing	Dimension or Value	Unit	Figure
L4 length, Route as coupled microstrip 100 ohm differential trace.	2 min to 16 max	inch	1
L4 length, Route as coupled stripline 100 ohm differential trace.	1.8 min to 14.4 max	inch	1

Differential Routing to PCI Express Connector	Dimension or Value	Unit	Figure
L4 length, Route as coupled microstrip 100 ohm differential trace.	0.25 to 14 max	inch	2
L4 length, Route as coupled stripline 100 ohm differential trace.	0.225 min to 12.6 max	inch	2

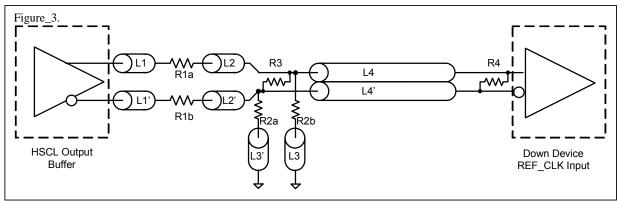




Alternative termination for LVDS and other common differential signals. Figure 3.

Vdiff	Vp-p	Vcm	R1	R2	R3	R4	Note
0.45 v	0.22v	1.08	33	150	100	100	
0.58	0.28	0.6	33	78.7	137	100	
0.80	0.40	0.6	33	78.7	none	100	ICS874003i-02 input compatible
0.60	0.3	1.2	33	174	140	100	Standard LVDS

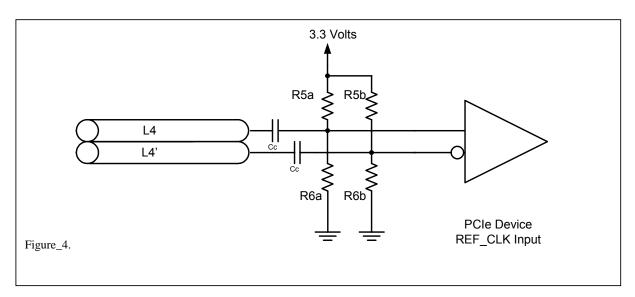
R1a = R1b = R1



R2a = R2b = R2

Cable connected AC coupled application, figure 4

Component	Value	Note
R5a,R5b	8.2K 5%	
R6a,R6b	1K 5%	
Cc	0.1 uF	
Vcm	0.350 volts	



General SMBus serial interface information for the ICS9DB403D

How to Write:

- · Controller (host) sends a start bit.
- Controller (host) sends the write address DC (h)
- ICS clock will acknowledge
- Controller (host) sends the begining byte location = N
- ICS clock will acknowledge
- Controller (host) sends the data byte count = X
- ICS clock will acknowledge
- Controller (host) starts sending Byte N through Byte N + X -1
- ICS clock will acknowledge each byte one at a time
- Controller (host) sends a Stop bit

How to Read:

- · Controller (host) will send start bit.
- Controller (host) sends the write address DC (h)
- ICS clock will acknowledge
- Controller (host) sends the begining byte location = N
- ICS clock will acknowledge
- Controller (host) will send a separate start bit.
- Controller (host) sends the read address DD (h)
- ICS clock will acknowledge
- ICS clock will send the data byte count = X
- ICS clock sends Byte N + X -1
- ICS clock sends Byte 0 through byte X (if X_(h) was written to byte 8).
- Controller (host) will need to acknowledge each byte
- Controllor (host) will send a not acknowledge bit
- · Controller (host) will send a stop bit

Ind	ex Block W	/rit	e Operation
Cor	ntroller (Host)		ICS (Slave/Receiver)
Т	starT bit		
Slav	e Address DC _(h)		
WR	WRite		
			ACK
Begi	nning Byte = N		
			ACK
Data	Byte Count = X		
			ACK
Begir	ning Byte N		
			ACK
	\rightarrow	'te	
	\rightarrow	X Byte	\Q
	\Q	×	\Q
			\Q
Byte	e N + X - 1		
			ACK
Р	stoP bit		

Ind	ex Block Rea	ad	Operation		
Con	troller (Host)	IC	S (Slave/Receiver)		
Т	starT bit				
Slave	Address DC _(h)				
WR	WRite				
			ACK		
Begir	nning Byte = N				
			ACK		
RT	Repeat starT				
Slave	Address DD _(h)				
RD	ReaD				
		ACK			
		Data Byte Count = X			
	ACK				
			Beginning Byte N		
	ACK				
		Ţ.	\Diamond		
	O	X Byte	\Q		
	O	×	\Q		
	\Q				
			Byte N + X - 1		
N	Not acknowledge				
Р	stoP bit				

SMBus Table: Frequency Select Register, READ/WRITE ADDRESS (DC/DD)

Byte	0 Pin#	Name	Control Function	Type	0	1	Default
Bit 7	-	PD_Mode	PD# drive mode	RW	driven	Hi-Z	0
Bit 6	-	STOP_Mode	SRC_Stop# drive mode	RW	driven	Hi-Z	0
Bit 5	-	PD_Polarity	Select PD polarity	RW	Low	High	0
Bit 4		Reserved	Reserved	RW	Reserved		X
Bit 3		Reserved	Reserved	RW	Reserved		Х
Bit 2	-	PLL_BW#	Select PLL BW	RW	High BW	Low BW	1
Bit 1	-	BYPASS#	BYPASS#/PLL	RW	fan-out	ZDB	1
Bit 0		SRC_DIV#	SRC Divide by 2 Select	RW	x/2	1x	1

SMBus Table: Output Control Register

By	te 1	Pin #	Name	Control Function	Туре	0	1	Default
Bit 7	-		Reserved	Reserved	RW	Rese	Reserved	
Bit 6	22,2	23	DIF_6	Output Enable	RW	Disable	Enable	1
Bit 5	19,2	20	DIF_5	Output Enable	RW	Disable	Enable	1
Bit 4	-		Reserved	Reserved	RW	Reserved		1
Bit 3	-		Reserved	Reserved	RW	Rese	erved	1
Bit 2	9,1	0	DIF_2	Output Enable	RW	Disable	Enable	1
Bit 1	6,7	7	DIF_1	Output Enable	RW	Disable	Enable	1
Bit 0	-		Reserved	Reserved	RW	Rese	erved	1

NOTE: The SMBus Output Enable Bit must be '1' AND the respective OE pin must be active for the output to run!

SMBus Table: OE Pin Control Register

By	te 2	Pin #	Name	Control Function	Type	0	1	Default
Bit 7		-	Reserved	Reserved	RW	Res	Reserved	
Bit 6	22	,23	DIF_6	DIF_6 Stoppable with OE6	RW	Free-run	Stoppable	0
Bit 5		-	Reserved	Reserved	RW	Res	Reserved	
Bit 4		-	Reserved	Reserved	RW	Res	Reserved	
Bit 3		-	Reserved	Reserved	RW	Res	Reserved	
Bit 2		-	Reserved	Reserved	RW	Reserved		0
Bit 1	6	,7	DIF_1	DIF_1 Stoppable with OE1	RW	Free-run	Stoppable	0
Bit 0		-	Reserved	Reserved	RW	Reserved		0

SMBus Table: Reserved Register

OWIDUS TUBIC. Heserved Hegister											
Byte	3 Pi	in #	Name	Control Function	Type	0	1	Default			
Bit 7				Reserved				Х			
Bit 6				Reserved				X			
Bit 5				Reserved				X			
Bit 4				Reserved				X			
Bit 3				Reserved				Х			
Bit 2				Reserved				X			
Bit 1				Reserved				X			
Bit 0				Reserved				Х			

SMBus Table: Vendor & Revision ID Register

Byt	te 4 Pir	1 #	Name	Control Function	Type	0	1	Default
Bit 7	=		RID3		R	-	-	0
Bit 6	-		RID2	REVISION ID	R	ı	-	0
Bit 5	-		RID1	NEVISION ID	R	1	-	1
Bit 4	-		RID0		R	-	-	1
Bit 3	-		VID3		R	•	-	0
Bit 2	-		VID2	VENDOR ID	R	-	-	0
Bit 1	- VID1		R	-	-	0		
Bit 0	-		VID0		R	-	-	1

SMBus Table: DEVICE ID

Byte	e 5 F	Pin #	Name	Control Function	Туре	0	1	Default	
Bit 7	-			Device ID 7 (MSB)	RW			0	
Bit 6	-			Device ID 6	RW			Χ	
Bit 5	-			Device ID 5	RW	Doving IF	Device ID is 83 Hex		
Bit 4	-			Device ID 4	RW		03 and 43	0	
Bit 3	-			Device ID 3	RW			0	
Bit 2	-			Device ID 2	RW	nex ioi	Hex for 9DB403		
Bit 1	-		Device ID 1 RW					1	
Bit 0	-			Device ID 0	RW			1	

SMBus Table: Byte Count Register

By	te 6 Pi	in #	Name	Control Function	Туре	0	1	Default
Bit 7	-		BC7		RW	ı	-	0
Bit 6	-		BC6		RW	•	-	0
Bit 5	-		BC5		RW	•	-	0
Bit 4	-		BC4	Writing to this register configures how	RW	-	-	0
Bit 3	-		BC3	many bytes will be read back.	RW	-	-	0
Bit 2	-		BC2		RW	-	-	1
Bit 1	-		BC1		RW	•	-	1
Bit 0	-		BC0		RW	-	-	1

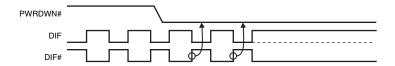
Note: Polarities in timing diagrams are shown OE_INV = 0. They are similar to OE_INV = 1.

PD#, Power Down

The PD# pin cleanly shuts off all clocks and places the device into a power saving mode. PD# must be asserted before shutting off the input clock or power to insure an orderly shutdown. PD is asynchronous active-low input for both powering down the device and powering up the device. When PD# is asserted, all clocks will be driven high, or tri-stated (depending on the PD# drive mode and Output control bits) before the PLL is shut down.

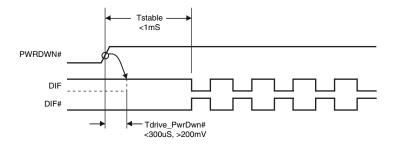
PD# Assertion

When PD# is sampled low by two consecutive rising edges of DIF#, all DIF outputs must be held High, or tri-stated (depending on the PD# drive mode and Output control bits) on the next High-Low transition of the DIF# outputs. When the PD# drive mode bit is set to '0', all clock outputs will be held with DIF driven High with 2 x I_{REF} and DIF# tri-stated. If the PD# drive mode bit is set to '1', both DIF and DIF# are tri-stated.



PD# De-assertion

Power-up latency is less than 1 ms. This is the time from de-assertion of the PD# pin, or VDD reaching 3.3V, or the time from valid SRC_IN clocks until the time that stable clocks are output from the device (PLL Locked). If the PD# drive mode bit is set to '1', all the DIF outputs must driven to a voltage of >200 mV within 300 us of PD# de-assertion.



SRC_STOP#

The SRC_STOP# signal is an active-low asynchronous input that cleanly stops and starts the DIF outputs. A valid clock must be present on SRC_IN for this input to work properly. The SRC_STOP# signal is de-bounced and must remain stable for two consecutive rising edges of DIF# to be recognized as a valid assertion or de-assertion.

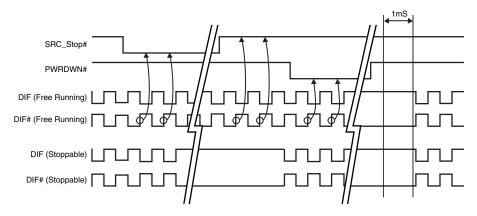
SRC STOP# - Assertion

Asserting SRC_STOP# causes all DIF outputs to stop after their next transition (if the control register settings allow the output to stop). When the SRC_STOP# drive bit is '0', the final state of all stopped DIF outputs is DIF = High and DIF# = Low. There is no change in output drive current. DIF is driven with $6x_{REF}$ DIF# is not driven, but pulled low by the termination. When the SRC_STOP# drive bit is '1', the final state of all DIF output pins is Low. Both DIF and DIF# are not driven.

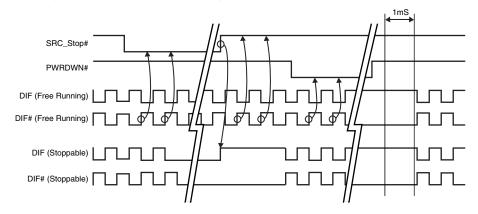
SRC_STOP# - De-assertion (transition from '0' to '1')

All stopped differential outputs resume normal operation in a glitch-free manner. The de-assertion latency to active outputs is 2-6 DIF clock periods, with all DIF outputs resuming simultaneously. If the SRC_STOP# drive control bit is '1' (tri-state), all stopped DIF outputs must be driven High (>200 mV) within 10 ns of de-assertion.

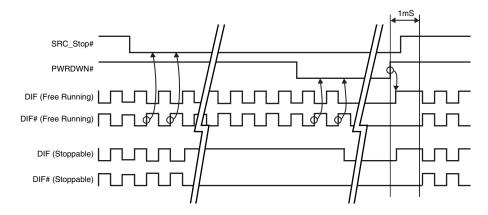
SRC_STOP_1 (SRC_Stop = Driven, PD = Driven)



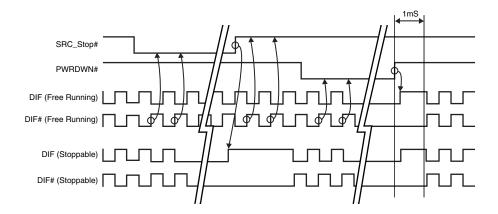
SRC_STOP_2 (SRC_Stop =Tristate, PD = Driven)



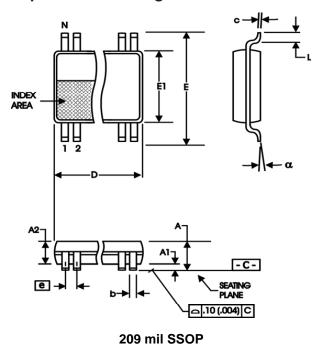
SRC_STOP_3 (**SRC_Stop** = **Driven**, **PD** = **Tristate**)



SRC_STOP_4 (SRC_Stop = Tristate, PD = Tristate)



28-pin SSOP Package Dimensions



209 mil SSOP

SYMBOL	In Millimeters COMMON DIMENSIONS		In Inches COMMON DIMENSIONS		
	MIN	MAX	MIN	MAX	
Α		2.00		.079	
A1	0.05		.002		
A2	1.65	1.85	.065	.073	
b	0.22	0.38	.009	.015	
С	0.09	0.25	.0035	.010	
D	SEE VARIATIONS		SEE VARIATIONS		
E	7.40	8.20	.291	.323	
E1	5.00	5.60	.197	.220	
е	0.65 BASIC		0.0256	BASIC	
L	0.55	0.95	.022	.037	
N					
α	0°	8°	0°	8°	

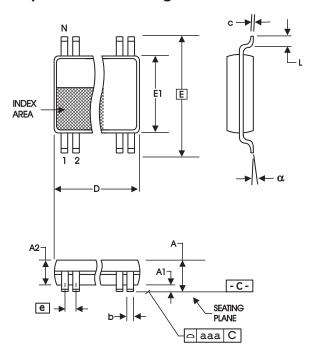
VARIATIONS

			D (inch)	
	MIN	MAX	MIN	MAX
28	9.90	10.50	.390	.413

Reference Doc.: JEDEC Publication 95, MO-150

10-0033

28-pin TSSOP Package Dimensions



4.40 mm. Body, 0.65 mm. Pitch TSSOP (173 mil) (25.6 mil)

	In Millimeters		In Inches		
SYMBOL	COMMON DIMENSIONS		COMMON DIMENSIONS		
	MIN	MAX	MIN	MAX	
Α		1.20		.047	
A1	0.05	0.15	.002	.006	
A2	0.80	1.05	.032	.041	
b	0.19	0.30	.007	.012	
С	0.09	0.20	.0035	.008	
D	SEE VARIATIONS		SEE VARIATIONS		
Е	6.40 BASIC		0.252 BASIC		
E1	4.30	4.50	.169	.177	
е	0.65 BASIC		0.0256	0.0256 BASIC	
L	0.45	0.75	.018	.030	
N	SEE VARIATIONS		SEE VAF	RIATIONS	
α	0°	8°	0°	8°	
aaa	-	0.10		.004	

VARIATIONS

N	D mm.		D (inch)	
	MIN	MAX	MIN	MAX
28	9.60	9.80	.378	.386

Reference Doc.: JEDEC Publication 95, MO-153

10-0035

Ordering Information

Part / Order Number	Marking	Shipping Packaging	Package	Temperature
9DB403DGLF	9DB403DGLF	Tubes	28-pin TSSOP	0 to +70° C
9DB403DGLFT	9DB403DGLF	Tape and Reel	28-pin TSSOP	0 to +70° C
9DB403DGILF	9DB403DGILF	Tubes	28-pin TSSOP	-40 to +85° C
9DB403DGILFT	9DB403DGILF	Tape and Reel	28-pin TSSOP	-40 to +85° C
9DB403DFLF	9DB403DFLF	Tubes	28-pin SSOP	0 to +70° C
9DB403DFLFT	9DB403DFLF	Tape and Reel	28-pin SSOP	0 to +70° C
9DB403DFILF	9DB403DFILF	Tubes	28-pin SSOP	-40 to +85° C
9DB403DFILFT	9DB403DFILF	Tape and Reel	28-pin SSOP	-40 to +85° C

[&]quot;LF" denotes Pb-free package, RoHS compliant

[&]quot;D" is the revision designator (will not correlate to datasheet revision)

Revision History

Rev.	Issue Date	Description	Page #
		Updated electrical characteristics for final data sheet	
Α	8/15/2006	2. Corrected references to 8 outputs (should be 4)	-
В	5/22/2007	Updated Polarity Inversion Table.	2
		Corrected SMBus table to eliminate non-existant outputs. This effects	
		bytes 1 and 2.	
С	1/16/2008	Changed PWD notation to Default in SMBus descriptions	11
D	2/29/2008	Added Input Clock Specs	6
Е	3/18/2008	Fixed typo in Input Clock Parameters	6
F	4/9/2008	Updated Input Clock Specs	6
G	8/19/2008	Corrected typos on Bytes 1 and 2.	11
	0/06/0000	 Updated Electrical Characteristics to add propagation delay and phase noise information. Corrected SMBus to reference pin numbers for 403 instead of 803 device. Removed references to OE controls that are not present on 403. Added SMBus electrical characteristics Added foot note about DIF input running in order for the SMBus interface to work Added foot note to Byte 1 about functionality of OE bits and OE pins. 	Various
H	8/26/2008	7. Corrected Block Diagram with proper OE pins indicated.	Various
	11/26/2008	Updated SMBus table - Byte0:Byte3.	11
J	2/6/2009	Added Industrial temp. specs and ordering information.	Various
K	7/13/2009	Updated general description and block diagram	1
		1. Clarified that Vih and Vil values were for Single ended inputs	
		2. Added separate Idd values for the 9DB403	
L	10/7/2009	3. Added Differential Clock input parameters.	Various

Innovate with IDT and accelerate your future networks. Contact:

www.IDT.com

For Sales

800-345-7015 408-284-8200 Fax: 408-284-2775

For Tech Support

408-284-6578 pcclockhelp@idt.com

Corporate Headquarters

Integrated Device Technology, Inc. 6024 Silver Creek Valley Road San Jose, CA 95138 United States 800 345 7015 +408 284 8200 (outside U.S.)

Asia Pacific and Japan

Integrated Device Technology Singapore (1997) Pte. Ltd. Reg. No. 199707558G 435 Orchard Road #20-03 Wisma Atria Singapore 238877 +65 6 887 5505

Europe

IDT Europe, Limited Prime House Barnett Wood Lane Leatherhead, Surrey United Kingdom KT22 7DE +44 1372 363 339



© 2006 Integrated Device Technology, Inc. All rights reserved. Product specifications subject to change without notice. IDT and the IDT logo are trademarks of Integrated Device Technology, Inc. Accelerated Thinking is a service mark of Integrated Device Technology, Inc. All other brands, product names and marks are or may be trademarks or registered trademarks used to identify products or services of their respective owners.

Printed in USA